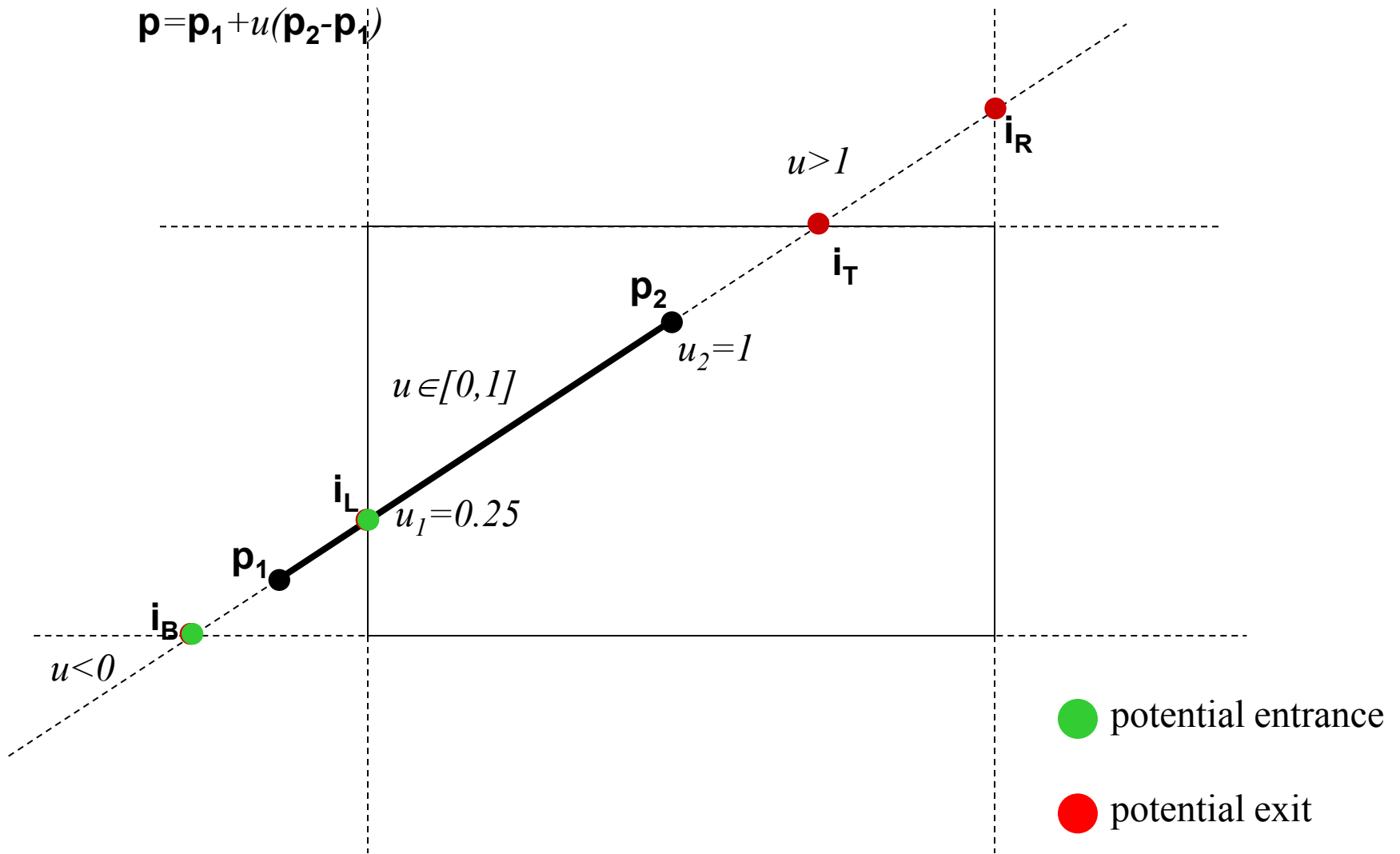
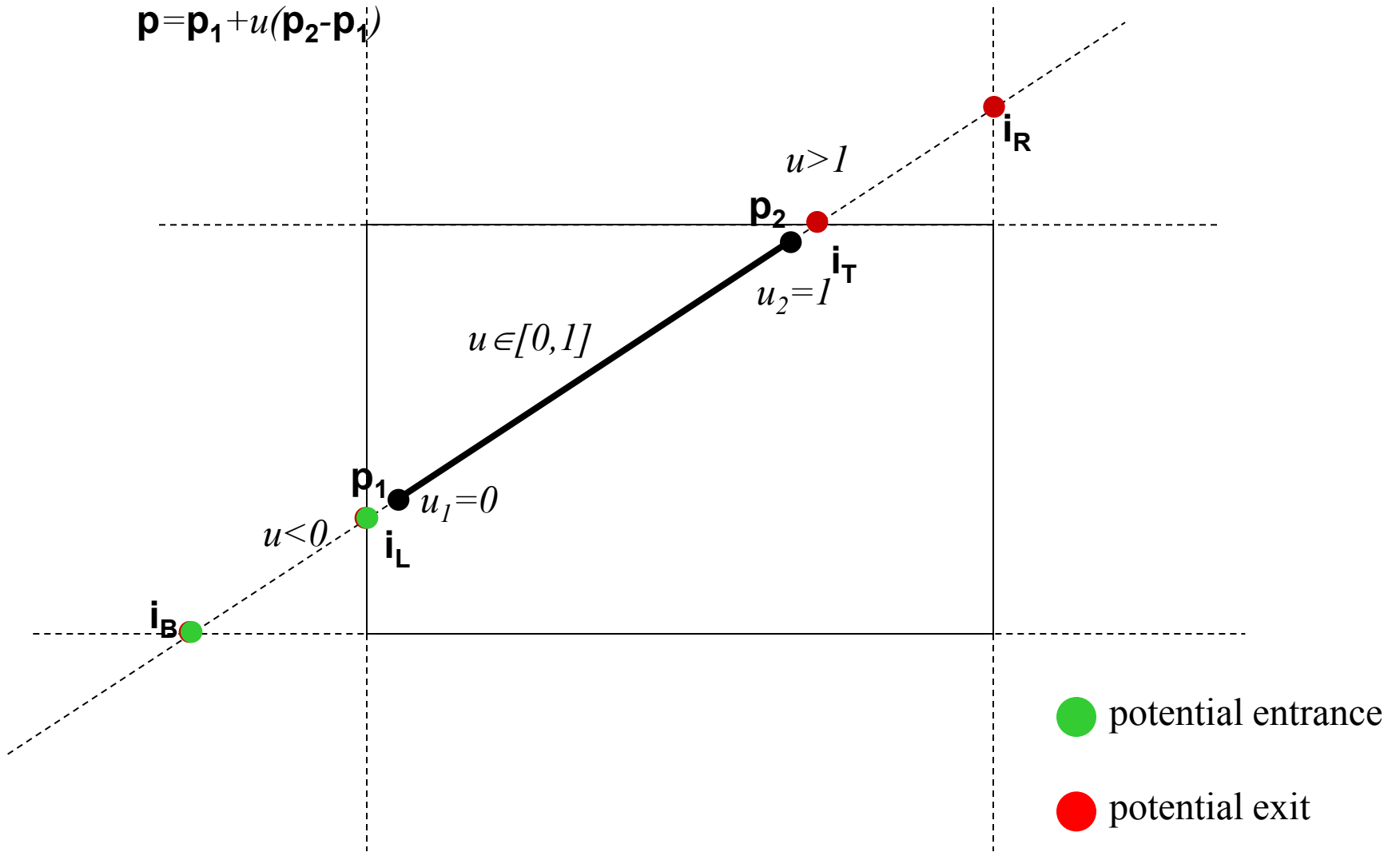


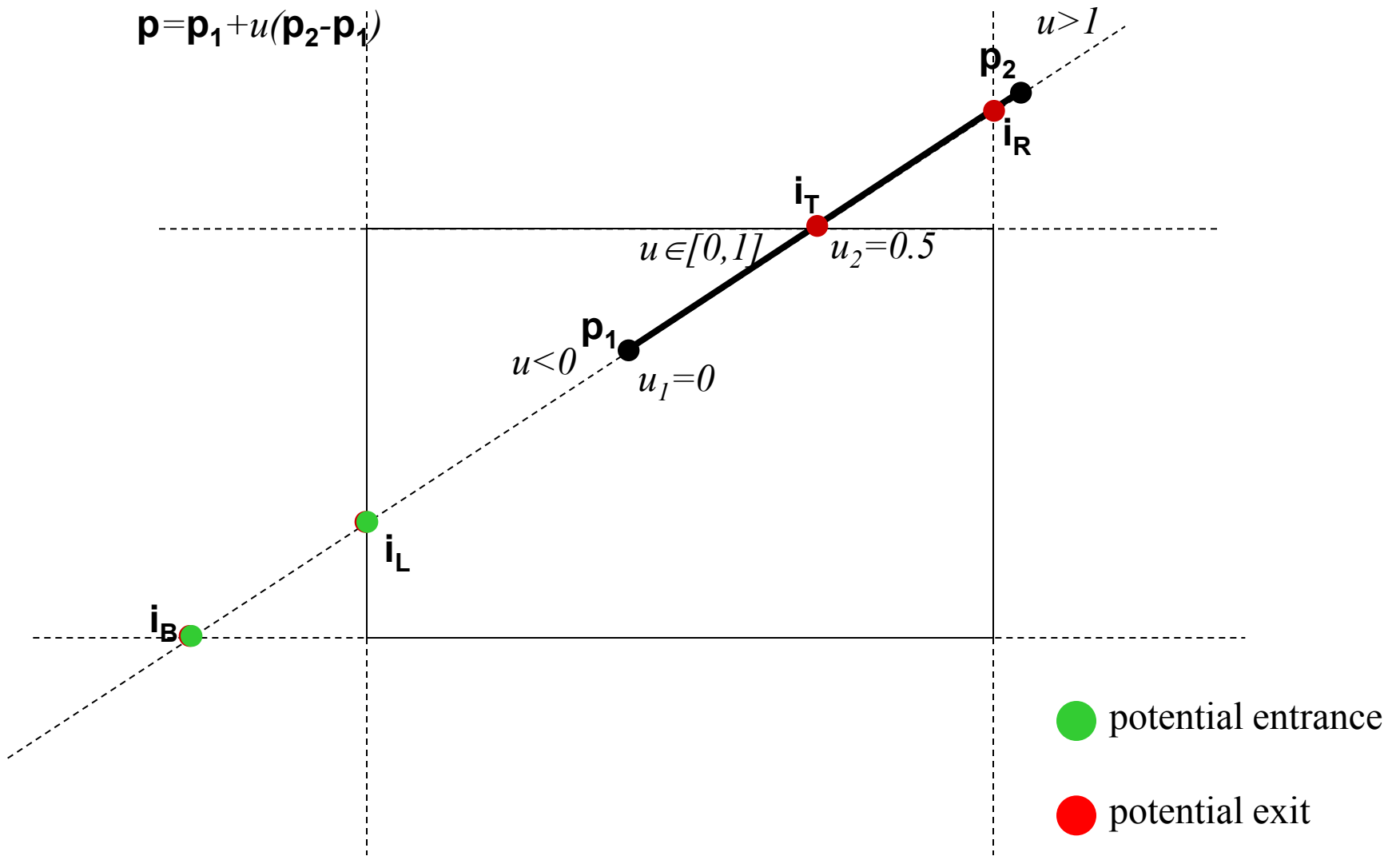
Liang-Barsky Line Clipping: Observation



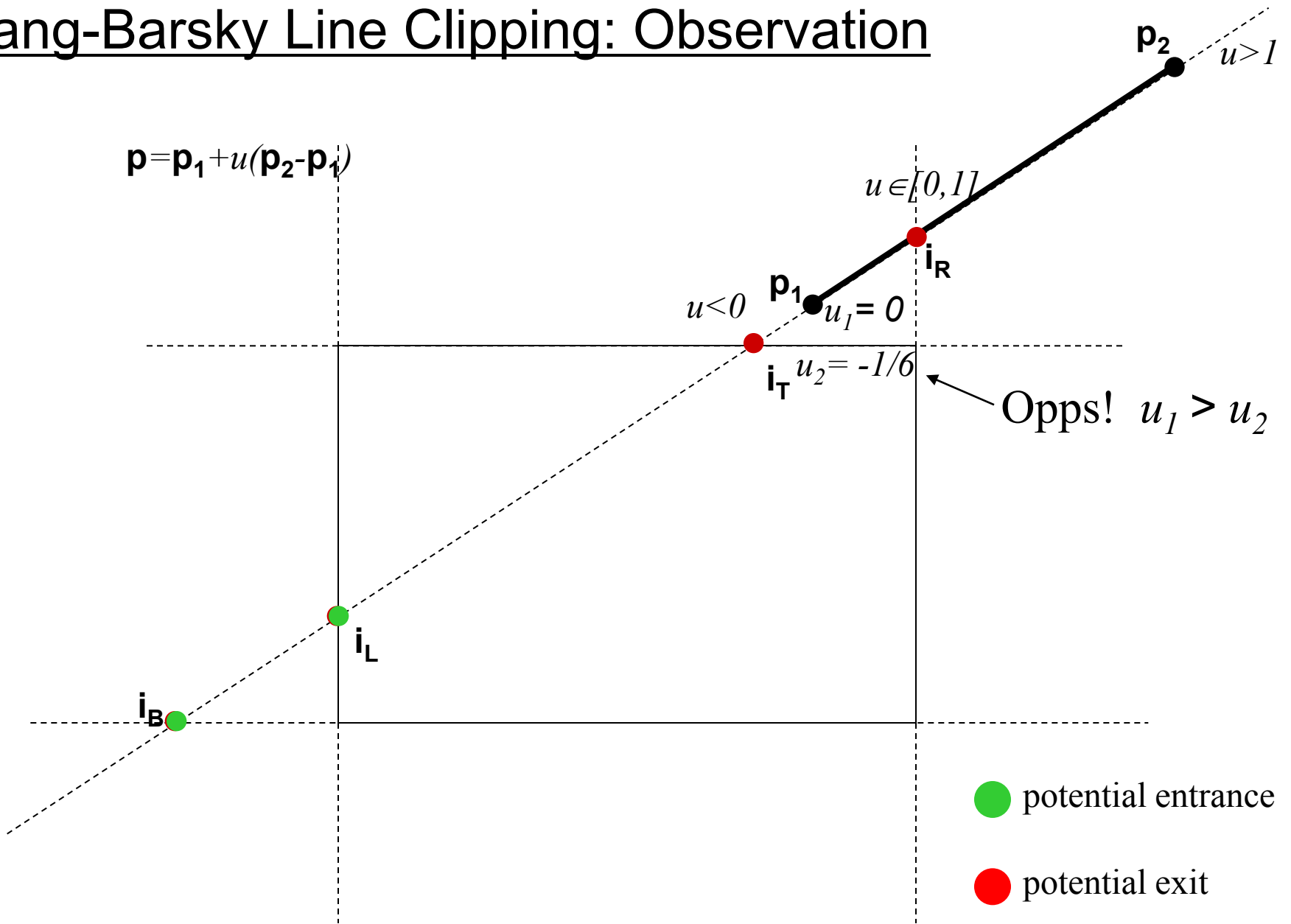
Liang-Barsky Line Clipping: Observation



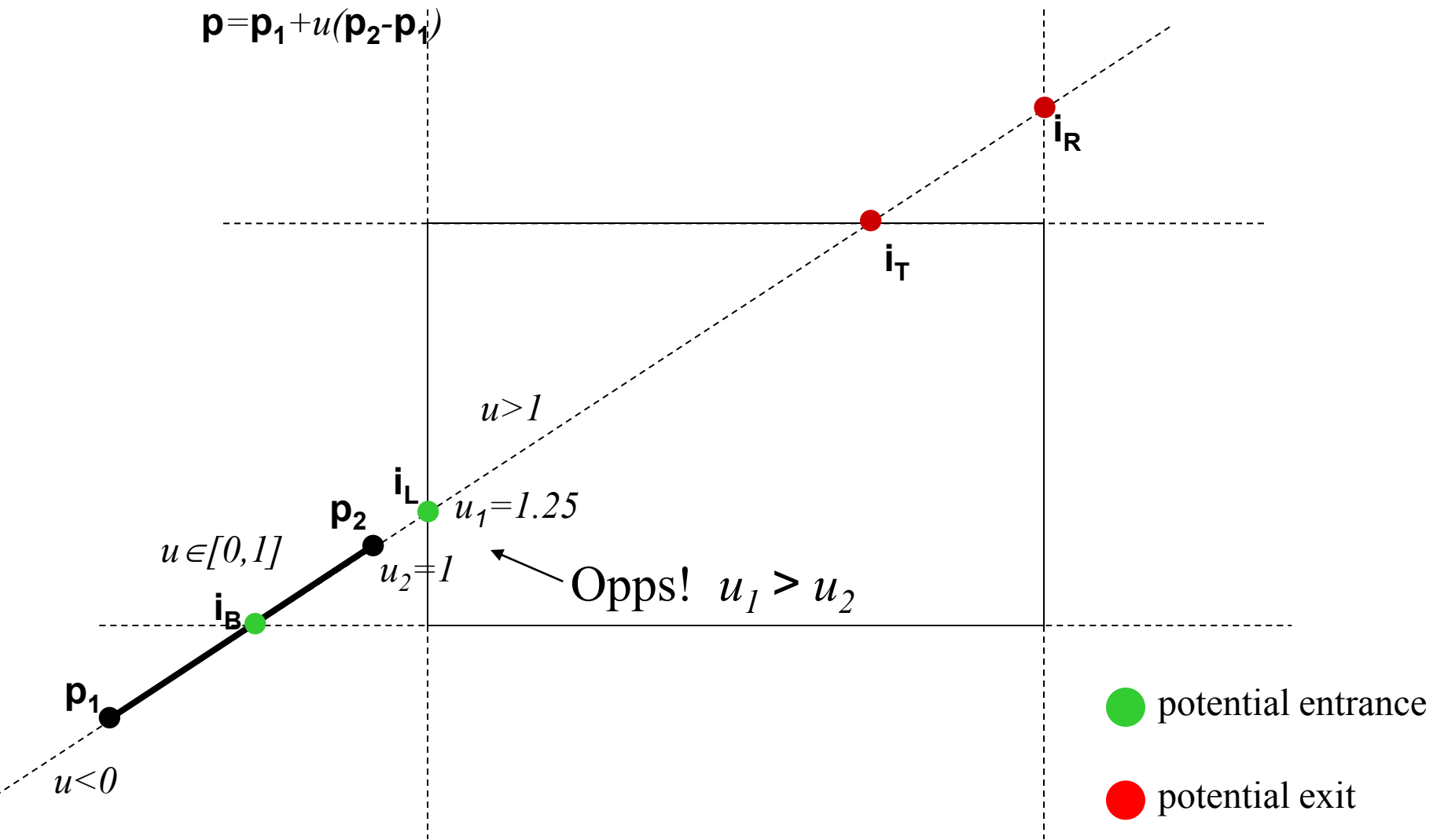
Liang-Barsky Line Clipping: Observation



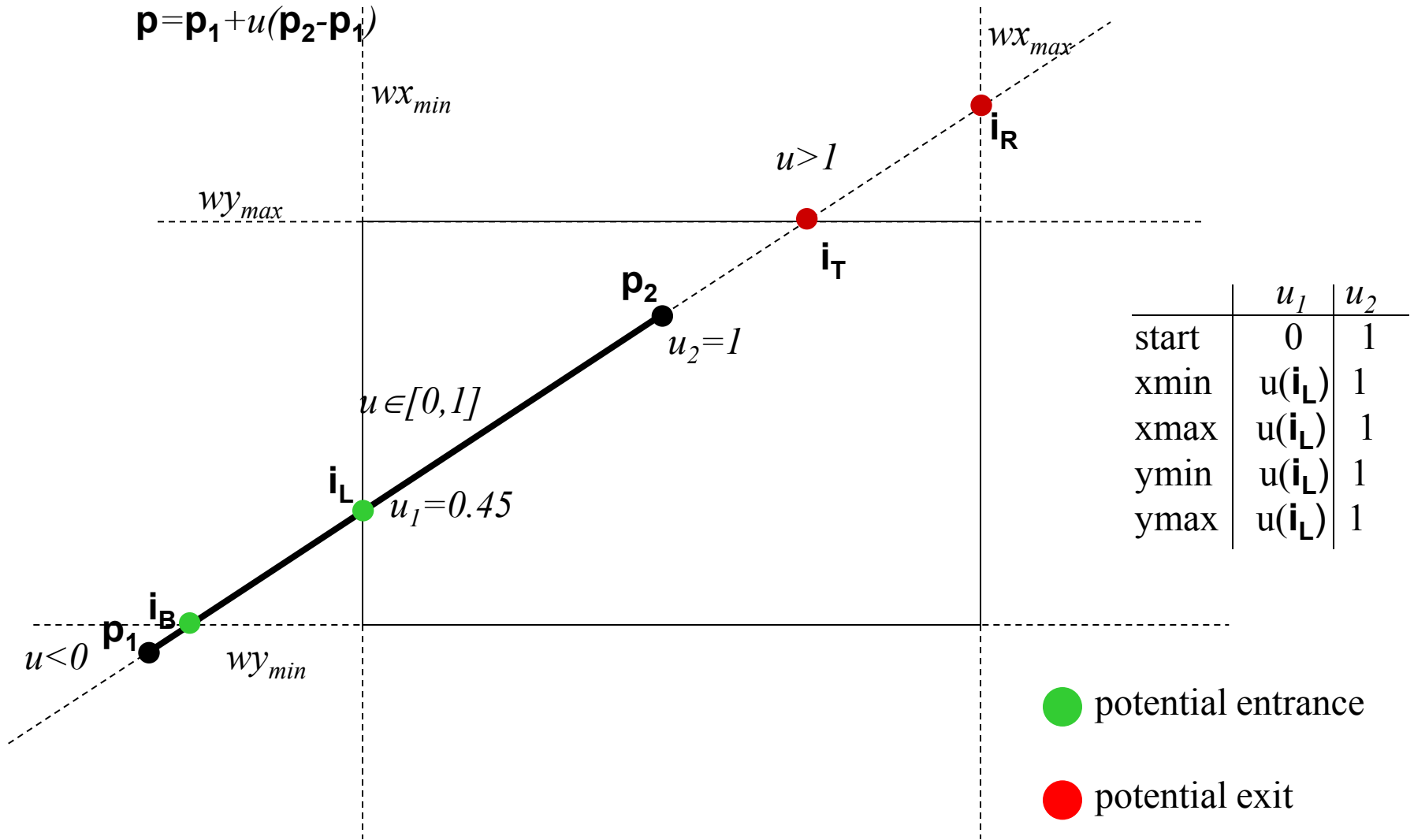
Liang-Barsky Line Clipping: Observation



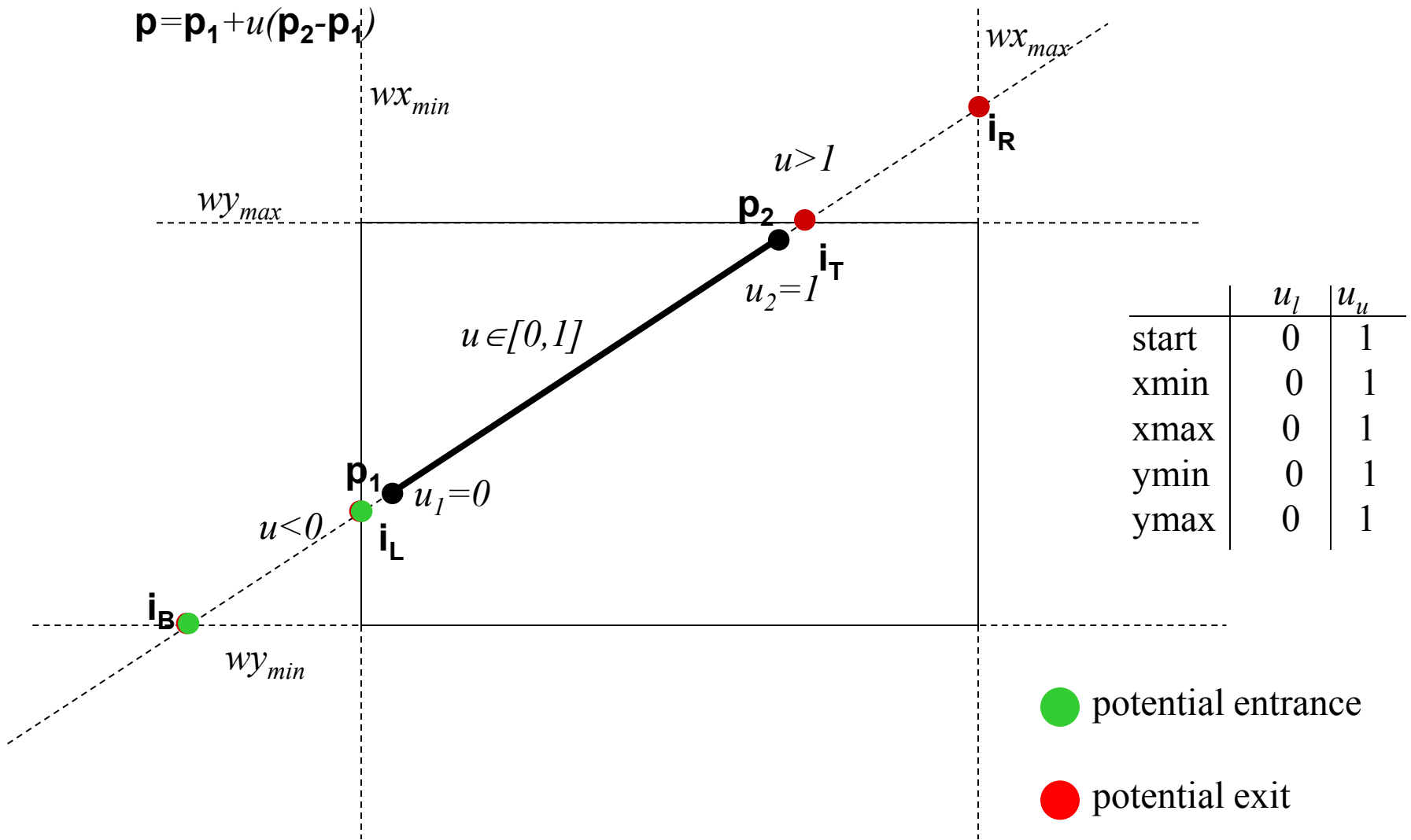
Liang-Barsky Line Clipping: Observation



Liang-Barsky: Algorithm

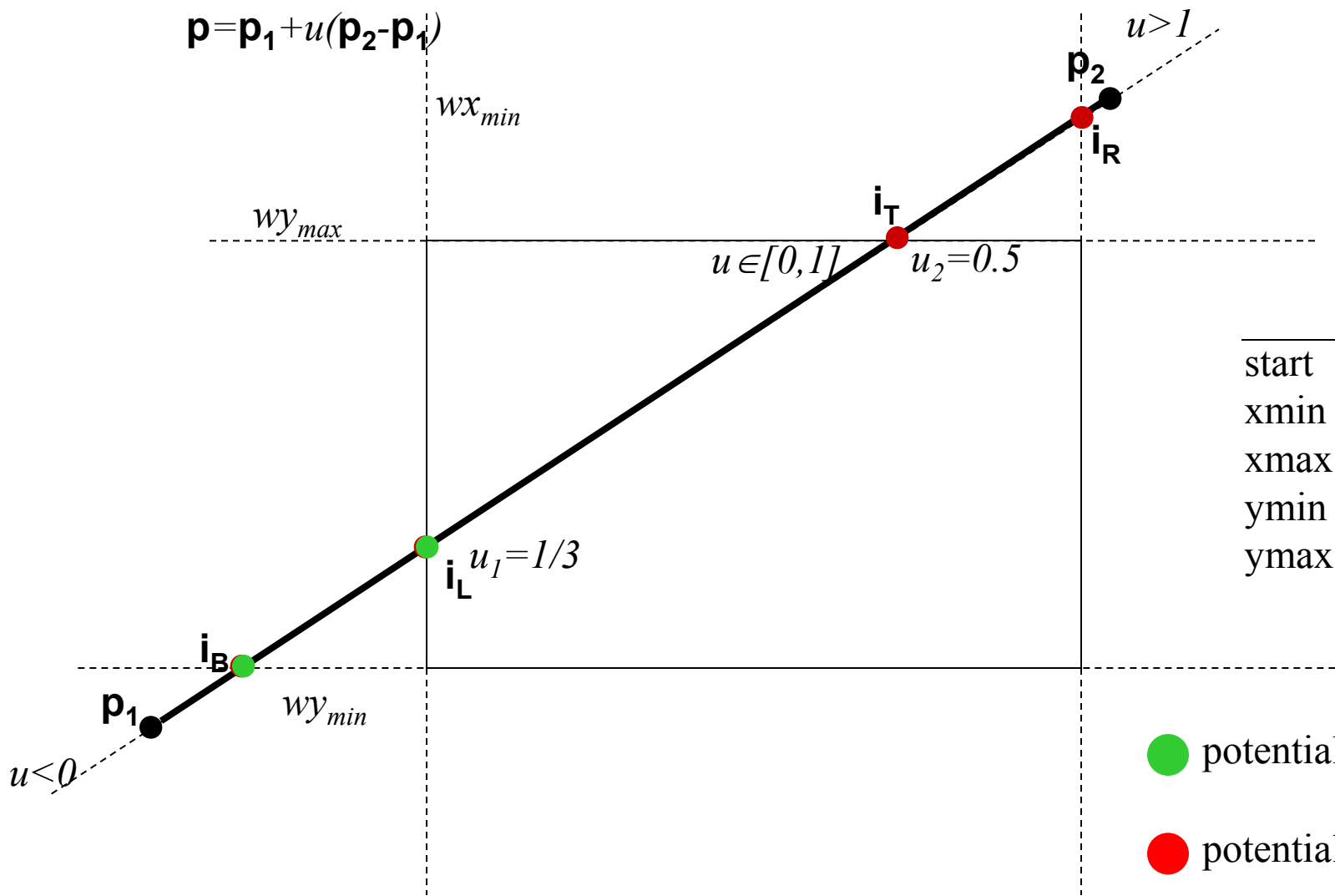


Liang-Barsky: Algorithm



Liang-Barsky: Algorithm

$$\mathbf{p} = \mathbf{p}_1 + u(\mathbf{p}_2 - \mathbf{p}_1)$$



	u_1	u_2
start	0	1
xmin	$u(i_L)$	1
xmax	$u(i_L)$	$u(i_R)$
ymin	$u(i_L)$	$u(i_R)$
ymax	$u(i_L)$	$u(i_T)$

- potential entrance
- potential exit

Liang-Barsky: Pseudo-Code

- Conceptually:

Test and update u_1 and u_2 against each of 4 edges of clip window and if u_1 and u_2 swap positions

return empty intersection

otherwise

use u_1 and u_2 to compute actual entrance and exit points

- Details:

-compute u of intersection with each window edge as follows:

separated coordinate
equations of
 $\mathbf{p} = \mathbf{p}_1 + u(\mathbf{p}_2 - \mathbf{p}_1)$

$$u_{x_{min}} = \frac{-\Delta x}{x_0 - x_{W_{min}}}, u_{x_{max}} = \frac{\Delta x}{x_{W_{max}} - x_0}$$
$$u_{y_{min}} = \frac{-\Delta y}{y_0 - y_{W_{min}}}, u_{y_{max}} = \frac{\Delta y}{y_{W_{max}} - y_0}$$

-horizontal or vertical lines: when numerator = 0 test sign of denominator

Liang-Barsky vs Cohen-Sutherland

- LB generally more efficient:
 - LB: updates of u_1 and u_2 use one division, window intersections computed only once with final u_1 and u_2
 - CS: may repeatedly calculate intersections along a line, even if line is totally exterior to clip window and each intersection computation uses division and multiplication